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Systems of coherent vectors

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Abstract. Some remarkable overcomplete sytems of vectors (called *systems of coherent vectors*), which offer almost the same facilities as an orthonormal basis and a simpler description of the action of the group, are defined in the case of an orthogonal \mathbb{R} -irreducible representation of a finite group *G* by following the analogy with the theory of coherent states.

1. Introduction

A vector space is usually described by using a basis, but certain overcomplete systems of vectors may also lead to useful descriptions. The method is mainly used in the case of infinite-dimensional spaces where the coherent states are such systems of vectors [5, 6, 8, 10, 12]. Among the applications in the case of finite-dimensional spaces there is a three-axis description of the honeycomb lattice [1,11], a four-axis description of the diamond structure [2,3] and the description of some \mathbb{Z} -modules in quasicrystal physics [4,7,9].

New applications of this method in the case of finite-dimensional real spaces seem to be possible, and our purpose is to develop the corresponding general mathematical formalism. Some of our results are inspired by the theory of coherent states [8, 10], but we think that certain constructions done in the simpler case of a finite-dimensional space might also offer some suggestions for the theory of coherent states.

2. Systems of coherent vectors

Let *G* be a finite group, $g : \mathbb{E}_n \longrightarrow \mathbb{E}_n$ be an orthogonal \mathbb{R} -irreducible representation of *G* in the Euclidean space $\mathbb{E}_n = (\mathbb{R}^n, \langle , \rangle)$, where $\langle x, y \rangle = \sum_{i=1}^n x_i y_i$, and let $u_1 \in \mathbb{E}_n$ be a fixed non-zero vector. The set *H* of all the elements $g \in G$ such that $gu_1 \in \{u_1, -u_1\}$ is a subgroup of *G*. Consider the space M = G/H of all the left cosets of *G* corresponding to *H*, and fix a set $\{g_1, g_2, \ldots, g_k\} \subset G$ containing one and only one representative of each coset. We can assume that g_1 is the unit element of *G*.

Let $e_1 = (1, 0, ..., 0)$, $e_2 = (0, 1, 0, ..., 0)$, ..., $e_n = (0, ..., 0, 1)$ be the vectors of the canonical basis of \mathbb{E}_n , and let $\mathcal{C} = \{u_1, u_2, ..., u_k\}$, where $u_i = g_i u_1$. Since $g_i u_1 = g_j u_1 \Longrightarrow g_i^{-1} g_j \in H$, that is, $u_i = u_j \Longrightarrow g_j \in g_i H$, the mapping

$$\Phi: M \longrightarrow \mathcal{C} \qquad \Phi(g_i) = u_i \tag{1}$$

is a bijection which allows us to identify the sets M and C. If g_i is replaced by another representative g'_i of the coset $g_i H$ then $g'_i u_1 \in \{u_i, -u_i\}$.

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For each $g \in G$ there exist the numbers $s_1^g, s_2^g, \ldots, s_k^g \in \{-1, 1\}$ and a permutation of the set $\{1, 2, \ldots, k\}$ denoted also by g such that

$$gu_i = s_{g(i)}^g u_{g(i)} \tag{2}$$

for all $i \in \{1, 2, ..., k\}$, and hence the subspace of \mathbb{E}_n generated by C is G-invariant. Since the considered representation of G in \mathbb{E}_n is \mathbb{R} -irreducible this subspace must coincide with \mathbb{E}_n , that is, C contains a basis of \mathbb{E}_n (in the following, we shall consider only the case when C is not itself a basis). We shall show that such a system leads to a useful description of \mathbb{E}_n , and call it a system of coherent vectors (SCV).

Theorem 1. *There is a constant* $\kappa \in (0, \infty)$ *such that*

$$x = \kappa \sum_{i=1}^{k} \langle x, u_i \rangle u_i = \kappa \sum_{y \in \mathcal{C}} \langle x, y \rangle y$$
(3)

for all $x \in \mathbb{E}_n$. In addition,

$$\langle x, y \rangle = \kappa \sum_{i=1}^{k} \langle x, u_i \rangle \langle u_i, y \rangle \qquad \|x\|^2 = \kappa \sum_{i=1}^{k} \langle x, u_i \rangle^2 \tag{4}$$

for all $x, y \in \mathbb{E}_n$.

Proof. The operator $U : \mathbb{E}_n \longrightarrow \mathbb{E}_n$, $Ux = \sum_{i=1}^k \langle x, u_i \rangle u_i$ satisfies the relation

$$U(gx) = \sum_{i=1}^{k} \langle gx, u_i \rangle u_i = \sum_{i=1}^{k} \langle gx, gu_i \rangle gu_i = g\left(\sum_{i=1}^{k} \langle x, u_i \rangle u_i\right) = g(Ux)$$

for all $x \in \mathbb{E}_n$, $g \in G$. Since our representation is in a real space, we cannot use Schur's lemma in order to obtain directly that U must have the form $Ux = \lambda x$. However, a real version of this lemma holds since U is a self-adjoint operator

$$\langle Ux, y \rangle = \left\langle \sum_{i=1}^{k} \langle x, u_i \rangle u_i, y \right\rangle = \sum_{i=1}^{k} \langle x, u_i \rangle \langle u_i, y \rangle = \langle x, Uy \rangle$$

and, hence, it has a real eigenvalue λ . Denoting $V = \{x \in \mathbb{E}_n | Ux = \lambda x\}$, from the relation $Ux = \lambda x \Longrightarrow U(gx) = \lambda(gx)$, it follows $g(V) \subset V$, and in view of the irreducibility of the representation of *G* in \mathbb{E}_n we must have $V = \mathbb{E}_n$; that is, $Ux = \lambda x$ for all $x \in \mathbb{E}_n$. From $\lambda e_1 = Ue_1 = \sum_{i=1}^k \langle e_1, u_i \rangle u_i$ we obtain $\lambda = \langle \lambda e_1, e_1 \rangle = \sum_{i=1}^k \langle e_1, u_i \rangle^2 \in (0, \infty)$, and hence there is $\kappa \in (0, \infty)$ such that $\lambda = 1/\kappa$. For any $y \in \mathbb{E}_n$ we obtain

$$\langle x, y \rangle = \left\langle \kappa \sum_{i=1}^{k} \langle x, u_i \rangle u_i, y \right\rangle = \kappa \sum_{i=1}^{k} \langle x, u_i \rangle \langle u_i, y \rangle$$
$$^2 = \kappa \sum_{i=1}^{k} \langle x, u_i \rangle^2.$$

whence $||x||^2 = \kappa \sum_{i=1}^k \langle x, u_i \rangle^2$.

Using the notations $|g\rangle = \Phi(g), \langle g|x\rangle = \langle \Phi(g), x\rangle$, the relation (3) can be rewritten in the form $x = \kappa \sum_{g \in M} \langle g|x\rangle |g\rangle$, in agreement with the theory of coherent states [10, relation (16)].

Example 1. The relations

 $a(x_1, x_2, x_3) = (-x_2, x_1, -x_3) \qquad b(x_1, x_2, x_3) = (x_1, -x_3, -x_2)$ (5) define an orthogonal \mathbb{R} -irreducible representation of the complete tetrahedral group $T_d = \overline{4}3m = \langle a, b | a^4 = b^2 = (ab)^3 = e \rangle$ in \mathbb{E}_3 . Choosing $u_1 = (1, 1, 1)$ we obtain the SCV

$$\mathcal{C} = \{(1, 1, 1), (1, -1, -1), (-1, 1, -1), (-1, -1, 1)\}.$$
(6)

One can also remark that the SCV obtained by starting from $u_1 = (1, 0, 0)$ coincides with the canonical basis {(1, 0, 0), (0, 1, 0), (0, 0, 1)}.

Example 2. Let $\tau = (1 + \sqrt{5})/2$. The relations

$$a(x_1, x_2, x_3) = \left(\frac{\tau - 1}{2}x_1 - \frac{\tau}{2}x_2 + \frac{1}{2}x_3, \frac{\tau}{2}x_1 + \frac{1}{2}x_2 + \frac{\tau - 1}{2}x_3, -\frac{1}{2}x_1 + \frac{\tau - 1}{2}x_2 + \frac{\tau}{2}x_3\right)$$

$$(7)$$

 $b(x_1, x_2, x_3) = (-x_1, -x_2, x_3)$

define an orthogonal \mathbb{R} -irreducible representation of the icosahedral group $Y = 235 = \langle a, b | a^5 = b^2 = (ab)^3 = e \rangle$ in \mathbb{E}_3 . Choosing $u_1 = (0, 1, \tau)$ we obtain [8] the SCV

$$C = \{(0, 1, \tau), (1, \tau, 0), (-1, \tau, 0), (-\tau, 0, 1), (0, -1, \tau), (\tau, 0, 1)\}$$
and choosing $u_1 = (1, 1, 1)$ we obtain the SCV $C = \{u_1, u_2, \dots, u_{10}\}$, where
$$(8)$$

$$\begin{aligned} & u_1 = (1, 1, 1) \text{ we obtain the SCV } \mathcal{L} = \{u_1, u_2, \dots, u_{10}\}, \text{ where} \\ & u_2 = (-1, 1, 1) \\ & u_5 = (0, \tau, \tau - 1) \\ & u_8 = (0, \tau, 1 - \tau) \\ & u_3 = (1, -1, 1) \\ & u_6 = (\tau - 1, 0, \tau) \\ & u_9 = (1 - \tau, 0, \tau) \\ & u_4 = (1, 1, -1) \\ & u_7 = (\tau, \tau - 1, 0) \\ & u_{10} = (\tau, 1 - \tau, 0). \end{aligned}$$
(9)

3. A geometric interpretation

A geometric interpretation of our formalism can be obtained by using some mathematical results obtained in connection with the strip projection method [4,8].

Lemma 1. The relation

$$T_g(\alpha_1, \alpha_2, \dots, \alpha_k) = (s_1^g \alpha_{g^{-1}(1)}, s_2^g \alpha_{g^{-1}(2)}, \dots, s_k^g \alpha_{g^{-1}(k)})$$
(10)

defines an orthogonal representation of G *in* \mathbb{E}_k *.*

Proof. Since $s_{(hg)(i)}^{hg} u_{(hg)(i)} = (hg)u_i = h(s_{g(i)}^g u_{g(i)}) = s_{g(i)}^g hu_{g(i)} = s_{g(i)}^g s_{(hg)(i)}^h u_{(hg)(i)}$ we obtain $s_{(hg)(i)}^{hg} = s_{g(i)}^g s_{(hg)(i)}^h$, that is, $s_i^{hg} = s_{h^{-1}(i)}^g s_i^h$, whence

$$T_{h}(T_{g}(\alpha_{1},...,\alpha_{k})) = T_{h}(s_{1}^{g}\alpha_{g^{-1}(1)},...,s_{k}^{g}\alpha_{g^{-1}(k)})$$

$$= (s_{1}^{h}s_{h^{-1}(1)}^{g}\alpha_{g^{-1}(h^{-1}(1))},...,s_{k}^{h}s_{h^{-1}(k)}^{g}\alpha_{g^{-1}(h^{-1}(k))})$$

$$= (s_{1}^{hg}\alpha_{(hg)^{-1}(1)},...,s_{k}^{hg}\alpha_{(hg)^{-1}(k)}) = T_{hg}(\alpha_{1},...,\alpha_{k}).$$
atton, $\langle T_{g}\alpha, T_{g}\beta \rangle = \sum_{i=1}^{k} (s_{i}^{s})^{2}\alpha_{g^{-1}(i)}\beta_{g^{-1}(i)} = \sum_{i=1}^{k} \alpha_{i}\beta_{i} = \langle \alpha, \beta \rangle.$

In addition, $\langle T_g \alpha, T_g \beta \rangle = \sum_{i=1}^{k} (s_i^g)^2 \alpha_{g^{-1}(i)} \beta_{g^{-1}(i)} = \sum_{i=1}^{k} \alpha_i \beta_i = \langle \alpha, \beta \rangle.$

Lemma 2. The subspaces

$$\mathbb{E}_{k}^{\parallel} = \{(\langle x, u_{1} \rangle, \langle x, u_{2} \rangle, \dots, \langle x, u_{k} \rangle) | x \in \mathbb{E}_{n}\}$$
(11)

$$\mathbb{E}_{k}^{\perp} = \left\{ (\alpha_{1}, \alpha_{2}, \dots, \alpha_{k}) \in \mathbb{E}_{k} \middle| \sum_{i=1}^{k} \alpha_{i} u_{i} = 0 \right\}$$
(12)

are orthogonal, *G*-invariant, and $\mathbb{E}_k = \mathbb{E}_k^{\parallel} \oplus \mathbb{E}_k^{\perp}$.

Proof. Indeed, dim
$$\mathbb{E}_{k}^{\parallel} = n$$
, dim $\mathbb{E}_{k}^{\perp} = k - n$, and
 $T_{g}(\langle x, u_{1} \rangle, \dots, \langle x, u_{k} \rangle) = (s_{1}^{g} \langle x, u_{g^{-1}(1)} \rangle, \dots, s_{k}^{g} \langle x, u_{g^{-1}(k)} \rangle))$
 $= (\langle x, g^{-1}u_{1} \rangle, \dots, \langle x, g^{-1}u_{k} \rangle) = (\langle gx, u_{1} \rangle, \dots, \langle gx, u_{k} \rangle)$
 $\sum_{i=1}^{k} s_{i}^{g} \alpha_{g^{-1}(i)} u_{i} = \sum_{i=1}^{k} \alpha_{i} s_{g(i)}^{g} u_{g(i)} = \sum_{i=1}^{k} \alpha_{i} gu_{i} = g\left(\sum_{i=1}^{k} \alpha_{i} u_{i}\right) = 0$
(13)
 $\sum_{i=1}^{k} \langle x, u_{i} \rangle \alpha_{i} = \left\langle x, \sum_{i=1}^{k} \alpha_{i} u_{i} \right\rangle = 0$

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for any $g \in G$, $x \in \mathbb{E}_n$, and $(\alpha_1, \ldots, \alpha_k) \in \mathbb{E}_k^{\perp}$.

Lemma 3. The orthogonal projector corresponding to \mathbb{E}_k^{\parallel} is

$$\pi: \mathbb{E}_k \longrightarrow \mathbb{E}_k \qquad \pi \alpha = \left(\kappa \sum_{i=1}^k \langle u_1, u_i \rangle \alpha_i, \dots, \kappa \sum_{i=1}^k \langle u_k, u_i \rangle \alpha_i\right).$$
(14)

Proof. If $\alpha = (\langle x, u_1 \rangle, \dots, \langle x, u_k \rangle) \in \mathbb{E}_k^{\parallel}$ then

$$\kappa \sum_{i=1}^{k} \langle u_j, u_i \rangle \alpha_i = \kappa \sum_{i=1}^{k} \langle u_j, u_i \rangle \langle x, u_i \rangle = \langle x, u_j \rangle$$

for all $j \in \{1, 2, ..., k\}$, that is, $\pi \alpha = \alpha$. For $\alpha \in \mathbb{E}_k^{\perp}$, from the relation

$$\kappa \sum_{i=1}^{k} \langle u_j, u_i \rangle \alpha_i = \kappa \left(u_j, \sum_{i=1}^{k} \alpha_i u_i \right) = 0$$

satisfied for all $j \in \{1, 2, ..., k\}$, it follows that $\pi \alpha = 0$.

Lemma 4. The isometry

$$S: \mathbb{E}_n \longrightarrow \mathbb{E}_k^{\parallel} \qquad Sx = (\sqrt{\kappa} \langle x, u_1 \rangle, \dots, \sqrt{\kappa} \langle x, u_k \rangle)$$
(15)

is an isomorphism of representations which allows us to identify the spaces \mathbb{E}_n and \mathbb{E}_k^{\parallel} .

Proof. The mapping *S* is an isometry

$$\langle Sx, Sy \rangle = \kappa \sum_{i=1}^{k} \langle x, u_i \rangle \langle y, u_i \rangle = \langle x, y \rangle$$

f (13) we have $T_g(Sx) = S(gx)$ for any $x \in \mathbb{E}_n, g \in G$.

and in view of (13) we have $T_g(Sx) = S(gx)$ for any $x \in \mathbb{E}_n$, $g \in G$. The representation of a vector $x \in \mathbb{E}_n$ as a linear combination of u_1, u_2, \dots, u_k is not

unique, but the next theorem shows that the canonical representation (3) is a privileged one, namely, the sum of the square of the coefficients takes its minimal value.

Theorem 2. Let $x \in \mathbb{E}_n$. If $x = \sum_{i=1}^k \alpha_i u_i$ then

(i)
$$\pi(\alpha_1, \dots, \alpha_k) = (\kappa \langle x, u_1 \rangle, \dots, \kappa \langle x, u_k \rangle)$$

(ii) $\sum_{i=1}^k \alpha_i^2 \ge \sum_{i=1}^k (\kappa \langle x, u_i \rangle)^2.$ (16)

Particularly,

$$\pi(\kappa\langle x, u_1\rangle, \dots, \kappa\langle x, u_k\rangle) = (\kappa\langle x, u_1\rangle, \dots, \kappa\langle x, u_k\rangle).$$
(17)

Proof. In view of lemma 3 we obtain

$$(\pi\alpha)_i = \kappa \sum_{j=1}^k \langle u_i, u_j \rangle \alpha_j = \kappa \left\langle u_i, \sum_{j=1}^k \alpha_j u_j \right\rangle = \kappa \langle u_i, x \rangle.$$

Since the vectors $\pi \alpha$ and $\alpha - \pi \alpha$ are orthogonal, we obtain

$$\sum_{i=1}^{k} \alpha_i^2 = \|\alpha\|^2 = \|\pi\alpha\|^2 + \|\alpha - \pi\alpha\|^2 \ge \|\pi\alpha\|^2 = \sum_{i=1}^{k} (\kappa \langle x, u_i \rangle)^2.$$

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The numbers $\kappa \langle x, u_1 \rangle, \ldots, \kappa \langle x, u_k \rangle$ are the *coordinates* of $x \in \mathbb{E}_n$ with respect to the SCV $\{u_1, \ldots, u_k\}$. One can remark that $\alpha_1, \ldots, \alpha_k$ are the coordinates of a vector $x \in \mathbb{E}_n$ with respect to $\{u_1, \ldots, u_k\}$ if and only if $\pi(\alpha_1, \ldots, \alpha_k) = (\alpha_1, \ldots, \alpha_k)$, that is, if and only if

$$\alpha_i = \kappa \sum_{j=1}^k \langle u_i, u_j \rangle \alpha_j \tag{18}$$

for all $i \in \{1, 2, ..., k\}$.

The space \mathbb{E}_k can be identified with the space of all the functions $\varphi : M \longrightarrow \mathbb{R}$ by associating the function $\varphi_{\alpha}(g_i) = \alpha_i$ with each $\alpha \in \mathbb{E}_k$. In this case, denoting $\langle h|g \rangle = \langle \Phi(h), \Phi(g) \rangle$, relation (18) becomes

$$\varphi(h) = \kappa \sum_{g \in M} \langle h | g \rangle \varphi(g) \tag{19}$$

in agreement with the theory of coherent states [10, relation (14)].

4. Description of linear operators in terms of an SCV

It is well known that an adequate description can simplify the solution of a problem. If the elements of \mathbb{E}_n are described by using their coordinates with respect to an SCV C then each transformation $g : \mathbb{E}_n \longrightarrow \mathbb{E}_n$ becomes a signed permutation

$$T_g(\alpha_1, \alpha_2, \ldots, \alpha_k) = (s_1^g \alpha_{g^{-1}(1)}, s_2^g \alpha_{g^{-1}(2)}, \ldots, s_k^g \alpha_{g^{-1}(k)})$$

and, consequently, the form of the *G*-invariant mathematical objects (operators, equations, etc) defined on \mathbb{E}_n becomes simpler. Some concrete applications of the description of \mathbb{E}_3 obtained by using the SCV {(1, 1, 1), (1, -1, -1), (-1, 1, -1), (-1, -1, 1)} can be found in [2, 3]. In this section we only present some general results concerning the description of the linear operators in terms of an SCV.

Let $A : \mathbb{E}_n \longrightarrow \mathbb{E}_n$ be a linear operator, \tilde{S} be the transpose of the matrix

$$S = \sqrt{\kappa} \begin{pmatrix} \langle u_1, e_1 \rangle & \cdots & \langle u_1, e_n \rangle \\ \cdots & \cdots & \ddots \\ \langle u_k, e_1 \rangle & \cdots & \langle u_k, e_n \rangle \end{pmatrix} \qquad \pi = \kappa \begin{pmatrix} \langle u_1, u_1 \rangle & \cdots & \langle u_1, u_k \rangle \\ \cdots & \cdots & \cdots \\ \langle u_k, u_1 \rangle & \cdots & \langle u_k, u_k \rangle \end{pmatrix}$$

and let

$$A = \begin{pmatrix} \langle e_1, Ae_1 \rangle & \cdots & \langle e_1, Ae_n \rangle \\ \cdots & \cdots & \ddots \\ \langle e_n, Ae_1 \rangle & \cdots & \langle e_n, Ae_n \rangle \end{pmatrix} \qquad A' = \kappa \begin{pmatrix} \langle u_1, Au_1 \rangle & \cdots & \langle u_1, Au_k \rangle \\ \cdots & \cdots & \cdots \\ \langle u_k, Au_1 \rangle & \cdots & \langle u_k, Au_k \rangle \end{pmatrix}$$

be the matrices associated with our operator with respect to the canonical basis $\{e_1, \ldots, e_n\}$ and the SCV $C = \{u_1, \ldots, u_k\}$, respectively.

Theorem 3. We have

$$S\tilde{S} = \pi$$
 $\tilde{S}S = I$ $A' = SA\tilde{S}$ $\operatorname{Tr} A = \operatorname{Tr} A'$ (20)

where I is the unit matrix.

Proof. Indeed,

$$\kappa \sum_{m=1}^{n} \langle u_i, e_m \rangle \langle u_j, e_m \rangle = \kappa \langle u_i, u_j \rangle$$

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$$\kappa \sum_{m=1}^{\kappa} \langle u_m, e_i \rangle \langle u_m, e_j \rangle = \langle e_i, e_j \rangle$$

$$\kappa \sum_{j=1}^{n} \sum_{m=1}^{n} \langle u_i, e_j \rangle \langle e_j, Ae_m \rangle \langle u_l, e_m \rangle = \kappa \langle u_i, Au_l \rangle$$

and

$$\operatorname{Tr} A' = \kappa \sum_{i=1}^{k} \langle u_i, Au_i \rangle = \kappa \sum_{i=1}^{k} \sum_{j=1}^{n} \sum_{m=1}^{n} \langle u_i, e_j \rangle \langle e_j, Ae_m \rangle \langle u_i, e_m \rangle$$
$$= \sum_{j=1}^{n} \sum_{m=1}^{n} \langle e_m, e_j \rangle \langle e_j, Ae_m \rangle = \sum_{j=1}^{n} \langle e_j, Ae_j \rangle = \operatorname{Tr} A.$$

Theorem 4. The operator $A : \mathbb{E}_n \longrightarrow \mathbb{E}_n$ is a self-adjoint operator if and only if the matrix A' is symmetric.

Proof. If A is self-adjoint then $\langle u_l, Au_m \rangle = \langle u_m, Au_l \rangle$ for all $l, m \in \{1, 2, ..., k\}$. Conversely, if this relation is satisfied, then

$$\langle e_i, Ae_j \rangle = \kappa^2 \sum_{l=1}^k \sum_{m=1}^k \langle e_i, u_l \rangle \langle u_l, Au_m \rangle \langle e_j, u_m \rangle$$

= $\kappa^2 \sum_{l=1}^k \sum_{m=1}^k \langle e_i, u_l \rangle \langle u_m, Au_l \rangle \langle e_j, u_m \rangle = \langle e_j, Ae_i \rangle.$

Theorem 5. Any eigenvalue of A is at the same time an eigenvalue of the matrix A'.

Proof. If $x \in \mathbb{E}_n$ is an eigenvector corresponding to λ then

 $A'(Sx) = (SA\tilde{S})(Sx) = S(Ax) = S(\lambda x) = \lambda(Sx)$

that is, Sx is an eigenvector of A' corresponding to the eigenvalue λ .

Theorem 6. If $A, B : \mathbb{E}_n \longrightarrow \mathbb{E}_n$ are two linear operators such that AB = BA, and A' and B' are the corresponding matrices with respect to C, then A'B' = B'A'.

Proof. We have $A'B' = (SA\tilde{S})(SB\tilde{S}) = S(AB)\tilde{S} = S(BA)\tilde{S} = B'A'$.

The derivative of a function $f : \mathbb{E}_n \longrightarrow \mathbb{R}$ with respect to a unit vector $v \in \mathbb{E}_n$ is usually defined as

$$\frac{\partial f}{\partial v}(x) = \lim_{t \to 0} \frac{1}{t} (f(x+tv) - f(x))$$

If $||u_1|| = 1$ then $||u_2|| = \cdots = ||u_k|| = 1$, and we have the relations

$$\frac{\partial}{\partial u_i} = \sum_{j=1}^n \langle u_i, e_j \rangle \frac{\partial}{\partial e_j} \qquad \frac{\partial}{\partial e_i} = \kappa \sum_{j=1}^k \langle e_i, u_j \rangle \frac{\partial}{\partial u_j}$$
(21)

which are useful in the case of differential equations and operators.

The description obtained by using an SCV can be regarded as a discrete version of the method of coherent states, and it may be a useful alternative to the usual description in certain applications. Generally, the use of an SCV leads to simpler expressions for the *G*-invariant objects, and hence a simplification of the mathematical formalism of certain models [2, 3].

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