## Systems of coherent vectors

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# Systems of coherent vectors 

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#### Abstract

Some remarkable overcomplete sytems of vectors (called systems of coherent vectors), which offer almost the same facilities as an orthonormal basis and a simpler description of the action of the group, are defined in the case of an orthogonal $\mathbb{R}$-irreducible representation of a finite group $G$ by following the analogy with the theory of coherent states.


## 1. Introduction

A vector space is usually described by using a basis, but certain overcomplete systems of vectors may also lead to useful descriptions. The method is mainly used in the case of infinitedimensional spaces where the coherent states are such systems of vectors [5, 6, 8, 10, 12]. Among the applications in the case of finite-dimensional spaces there is a three-axis description of the honeycomb lattice [1,11], a four-axis description of the diamond structure [2,3] and the description of some $\mathbb{Z}$-modules in quasicrystal physics $[4,7,9]$.

New applications of this method in the case of finite-dimensional real spaces seem to be possible, and our purpose is to develop the corresponding general mathematical formalism. Some of our results are inspired by the theory of coherent states [8, 10], but we think that certain constructions done in the simpler case of a finite-dimensional space might also offer some suggestions for the theory of coherent states.

## 2. Systems of coherent vectors

Let $G$ be a finite group, $g: \mathbb{E}_{n} \longrightarrow \mathbb{E}_{n}$ be an orthogonal $\mathbb{R}$-irreducible representation of $G$ in the Euclidean space $\mathbb{E}_{n}=\left(\mathbb{R}^{n},\langle\rangle,\right)$, where $\langle x, y\rangle=\sum_{i=1}^{n} x_{i} y_{i}$, and let $u_{1} \in \mathbb{E}_{n}$ be a fixed non-zero vector. The set $H$ of all the elements $g \in G$ such that $g u_{1} \in\left\{u_{1},-u_{1}\right\}$ is a subgroup of $G$. Consider the space $M=G / H$ of all the left cosets of $G$ corresponding to $H$, and fix a set $\left\{g_{1}, g_{2}, \ldots, g_{k}\right\} \subset G$ containing one and only one representative of each coset. We can assume that $g_{1}$ is the unit element of $G$.

Let $e_{1}=(1,0, \ldots, 0), e_{2}=(0,1,0, \ldots, 0), \ldots, e_{n}=(0, \ldots, 0,1)$ be the vectors of the canonical basis of $\mathbb{E}_{n}$, and let $\mathcal{C}=\left\{u_{1}, u_{2}, \ldots, u_{k}\right\}$, where $u_{i}=g_{i} u_{1}$. Since $g_{i} u_{1}=g_{j} u_{1} \Longrightarrow g_{i}^{-1} g_{j} \in H$, that is, $u_{i}=u_{j} \Longrightarrow g_{j} \in g_{i} H$, the mapping

$$
\begin{equation*}
\Phi: M \longrightarrow \mathcal{C} \quad \Phi\left(g_{i}\right)=u_{i} \tag{1}
\end{equation*}
$$

is a bijection which allows us to identify the sets $M$ and $\mathcal{C}$. If $g_{i}$ is replaced by another representative $g_{i}^{\prime}$ of the coset $g_{i} H$ then $g_{i}^{\prime} u_{1} \in\left\{u_{i},-u_{i}\right\}$.

For each $g \in G$ there exist the numbers $s_{1}^{g}, s_{2}^{g}, \ldots, s_{k}^{g} \in\{-1,1\}$ and a permutation of the set $\{1,2, \ldots, k\}$ denoted also by $g$ such that

$$
\begin{equation*}
g u_{i}=s_{g(i)}^{g} u_{g(i)} \tag{2}
\end{equation*}
$$

for all $i \in\{1,2, \ldots, k\}$, and hence the subspace of $\mathbb{E}_{n}$ generated by $\mathcal{C}$ is $G$-invariant. Since the considered representation of $G$ in $\mathbb{E}_{n}$ is $\mathbb{R}$-irreducible this subspace must coincide with $\mathbb{E}_{n}$, that is, $\mathcal{C}$ contains a basis of $\mathbb{E}_{n}$ (in the following, we shall consider only the case when $\mathcal{C}$ is not itself a basis). We shall show that such a system leads to a useful description of $\mathbb{E}_{n}$, and call it a system of coherent vectors (SCV).
Theorem 1. There is a constant $\kappa \in(0, \infty)$ such that

$$
\begin{equation*}
x=\kappa \sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle u_{i}=\kappa \sum_{y \in \mathcal{C}}\langle x, y\rangle y \tag{3}
\end{equation*}
$$

for all $x \in \mathbb{E}_{n}$. In addition,

$$
\begin{equation*}
\langle x, y\rangle=\kappa \sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle\left\langle u_{i}, y\right\rangle \quad\|x\|^{2}=\kappa \sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle^{2} \tag{4}
\end{equation*}
$$

for all $x, y \in \mathbb{E}_{n}$.
Proof. The operator $U: \mathbb{E}_{n} \longrightarrow \mathbb{E}_{n}, U x=\sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle u_{i}$ satisfies the relation

$$
U(g x)=\sum_{i=1}^{k}\left\langle g x, u_{i}\right\rangle u_{i}=\sum_{i=1}^{k}\left\langle g x, g u_{i}\right\rangle g u_{i}=g\left(\sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle u_{i}\right)=g(U x)
$$

for all $x \in \mathbb{E}_{n}, g \in G$. Since our representation is in a real space, we cannot use Schur's lemma in order to obtain directly that $U$ must have the form $U x=\lambda x$. However, a real version of this lemma holds since $U$ is a self-adjoint operator

$$
\langle U x, y\rangle=\left\langle\sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle u_{i}, y\right\rangle=\sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle\left\langle u_{i}, y\right\rangle=\langle x, U y\rangle
$$

and, hence, it has a real eigenvalue $\lambda$. Denoting $V=\left\{x \in \mathbb{E}_{n} \mid U x=\lambda x\right\}$, from the relation $U x=\lambda x \Longrightarrow U(g x)=\lambda(g x)$, it follows $g(V) \subset V$, and in view of the irreducibility of the representation of $G$ in $\mathbb{E}_{n}$ we must have $V=\mathbb{E}_{n}$; that is, $U x=\lambda x$ for all $x \in \mathbb{E}_{n}$. From $\lambda e_{1}=U e_{1}=\sum_{i=1}^{k}\left\langle e_{1}, u_{i}\right\rangle u_{i}$ we obtain $\lambda=\left\langle\lambda e_{1}, e_{1}\right\rangle=\sum_{i=1}^{k}\left\langle e_{1}, u_{i}\right\rangle^{2} \in(0, \infty)$, and hence there is $\kappa \in(0, \infty)$ such that $\lambda=1 / \kappa$. For any $y \in \mathbb{E}_{n}$ we obtain

$$
\langle x, y\rangle=\left\langle\kappa \sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle u_{i}, y\right\rangle=\kappa \sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle\left\langle u_{i}, y\right\rangle
$$

whence $\|x\|^{2}=\kappa \sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle^{2}$.
Using the notations $|g\rangle=\Phi(g),\langle g \mid x\rangle=\langle\Phi(g), x\rangle$, the relation (3) can be rewritten in the form $x=\kappa \sum_{g \in M}\langle g \mid x\rangle|g\rangle$, in agreement with the theory of coherent states [10, relation (16)].

Example 1. The relations

$$
\begin{equation*}
a\left(x_{1}, x_{2}, x_{3}\right)=\left(-x_{2}, x_{1},-x_{3}\right) \quad b\left(x_{1}, x_{2}, x_{3}\right)=\left(x_{1},-x_{3},-x_{2}\right) \tag{5}
\end{equation*}
$$

define an orthogonal $\mathbb{R}$-irreducible representation of the complete tetrahedral group $T_{d}=$ $\overline{4} 3 m=\left\langle a, b \mid a^{4}=b^{2}=(a b)^{3}=e\right\rangle$ in $\mathbb{E}_{3}$. Choosing $u_{1}=(1,1,1)$ we obtain the SCV

$$
\begin{equation*}
\mathcal{C}=\{(1,1,1),(1,-1,-1),(-1,1,-1),(-1,-1,1)\} \tag{6}
\end{equation*}
$$

One can also remark that the SCV obtained by starting from $u_{1}=(1,0,0)$ coincides with the canonical basis $\{(1,0,0),(0,1,0),(0,0,1)\}$.

Example 2. Let $\tau=(1+\sqrt{5}) / 2$. The relations
$a\left(x_{1}, x_{2}, x_{3}\right)=\left(\frac{\tau-1}{2} x_{1}-\frac{\tau}{2} x_{2}+\frac{1}{2} x_{3}, \frac{\tau}{2} x_{1}+\frac{1}{2} x_{2}\right.$

$$
\begin{equation*}
\left.+\frac{\tau-1}{2} x_{3},-\frac{1}{2} x_{1}+\frac{\tau-1}{2} x_{2}+\frac{\tau}{2} x_{3}\right) \tag{7}
\end{equation*}
$$

$b\left(x_{1}, x_{2}, x_{3}\right)=\left(-x_{1},-x_{2}, x_{3}\right)$
define an orthogonal $\mathbb{R}$-irreducible representation of the icosahedral group $Y=235=$ $\left\langle a, b \mid a^{5}=b^{2}=(a b)^{3}=e\right\rangle$ in $\mathbb{E}_{3}$. Choosing $u_{1}=(0,1, \tau)$ we obtain [8] the SCV

$$
\begin{equation*}
\mathcal{C}=\{(0,1, \tau),(1, \tau, 0),(-1, \tau, 0),(-\tau, 0,1),(0,-1, \tau),(\tau, 0,1)\} \tag{8}
\end{equation*}
$$

and choosing $u_{1}=(1,1,1)$ we obtain the $\operatorname{SCV} \mathcal{C}=\left\{u_{1}, u_{2}, \ldots, u_{10}\right\}$, where

$$
\begin{array}{lll}
u_{2}=(-1,1,1) & u_{5}=(0, \tau, \tau-1) & u_{8}=(0, \tau, 1-\tau) \\
u_{3}=(1,-1,1) & u_{6}=(\tau-1,0, \tau) & u_{9}=(1-\tau, 0, \tau)  \tag{9}\\
u_{4}=(1,1,-1) & u_{7}=(\tau, \tau-1,0) & u_{10}=(\tau, 1-\tau, 0) .
\end{array}
$$

## 3. A geometric interpretation

A geometric interpretation of our formalism can be obtained by using some mathematical results obtained in connection with the strip projection method [4, 8].
Lemma 1. The relation

$$
\begin{equation*}
T_{g}\left(\alpha_{1}, \alpha_{2}, \ldots, \alpha_{k}\right)=\left(s_{1}^{g} \alpha_{g^{-1}(1)}, s_{2}^{g} \alpha_{g^{-1}(2)}, \ldots, s_{k}^{g} \alpha_{g^{-1}(k)}\right) \tag{10}
\end{equation*}
$$

defines an orthogonal representation of $G$ in $\mathbb{E}_{k}$.
Proof. Since $s_{(h g)(i)}^{h g} u_{(h g)(i)}=(h g) u_{i}=h\left(s_{g(i)}^{g} u_{g(i)}\right)=s_{g(i)}^{g} h u_{g(i)}=s_{g(i)}^{g} s_{(h g)(i)}^{h} u_{(h g)(i)}$ we obtain $s_{(h g)(i)}^{h g}=s_{g(i)}^{g} s_{(h g)(i)}^{h}$, that is, $s_{i}^{h g}=s_{h^{-1}(i)}^{g} s_{i}^{h}$, whence

$$
\begin{aligned}
T_{h}\left(T_{g}\left(\alpha_{1}, \ldots, \alpha_{k}\right)\right) & =T_{h}\left(s_{1}^{g} \alpha_{g^{-1}(1)}, \ldots, s_{k}^{g} \alpha_{g^{-1}(k)}\right) \\
& =\left(s_{1}^{h} s_{h^{-1}(1)}^{g} \alpha_{g^{-1}\left(h^{-1}(1)\right)}, \ldots, s_{k}^{h} s_{h^{-1}(k)}^{g} \alpha_{g^{-1}\left(h^{-1}(k)\right)}\right) \\
& =\left(s_{1}^{h g} \alpha_{(h g)^{-1}(1)}, \ldots, s_{k}^{h g} \alpha_{(h g)^{-1}(k)}\right)=T_{h g}\left(\alpha_{1}, \ldots, \alpha_{k}\right) .
\end{aligned}
$$

In addition, $\left\langle T_{g} \alpha, T_{g} \beta\right\rangle=\sum_{i=1}^{k}\left(s_{i}^{g}\right)^{2} \alpha_{g^{-1}(i)} \beta_{g^{-1}(i)}=\sum_{i=1}^{k} \alpha_{i} \beta_{i}=\langle\alpha, \beta\rangle$.
Lemma 2. The subspaces

$$
\begin{align*}
& \mathbb{E}_{k}^{\|}=\left\{\left(\left\langle x, u_{1}\right\rangle,\left\langle x, u_{2}\right\rangle, \ldots,\left\langle x, u_{k}\right\rangle\right) \mid x \in \mathbb{E}_{n}\right\}  \tag{11}\\
& \mathbb{E}_{k}^{\perp}=\left\{\left(\alpha_{1}, \alpha_{2}, \ldots, \alpha_{k}\right) \in \mathbb{E}_{k} \mid \sum_{i=1}^{k} \alpha_{i} u_{i}=0\right\} \tag{12}
\end{align*}
$$

are orthogonal, $G$-invariant, and $\mathbb{E}_{k}=\mathbb{E}_{k}^{\|} \oplus \mathbb{E}_{k}^{\perp}$.
Proof. Indeed, $\operatorname{dim} \mathbb{E}_{k}^{\|}=n, \operatorname{dim} \mathbb{E}_{k}^{\perp}=k-n$, and
$T_{g}\left(\left\langle x, u_{1}\right\rangle, \ldots,\left\langle x, u_{k}\right\rangle\right)=\left(s_{1}^{g}\left\langle x, u_{g^{-1}(1)}\right\rangle, \ldots, s_{k}^{g}\left\langle x, u_{g^{-1}(k)}\right\rangle\right)$

$$
\begin{equation*}
=\left(\left\langle x, g^{-1} u_{1}\right\rangle, \ldots,\left\langle x, g^{-1} u_{k}\right\rangle\right)=\left(\left\langle g x, u_{1}\right\rangle, \ldots,\left\langle g x, u_{k}\right\rangle\right) \tag{13}
\end{equation*}
$$

$\sum_{i=1}^{k} s_{i}^{g} \alpha_{g^{-1}(i)} u_{i}=\sum_{i=1}^{k} \alpha_{i} s_{g(i)}^{g} u_{g(i)}=\sum_{i=1}^{k} \alpha_{i} g u_{i}=g\left(\sum_{i=1}^{k} \alpha_{i} u_{i}\right)=0$
$\sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle \alpha_{i}=\left\langle x, \sum_{i=1}^{k} \alpha_{i} u_{i}\right\rangle=0$
for any $g \in G, x \in \mathbb{E}_{n}$, and $\left(\alpha_{1}, \ldots, \alpha_{k}\right) \in \mathbb{E}_{k}^{\perp}$.
Lemma 3. The orthogonal projector corresponding to $\mathbb{E}_{k}^{\|}$is

$$
\begin{equation*}
\pi: \mathbb{E}_{k} \longrightarrow \mathbb{E}_{k} \quad \pi \alpha=\left(\kappa \sum_{i=1}^{k}\left\langle u_{1}, u_{i}\right\rangle \alpha_{i}, \ldots, \kappa \sum_{i=1}^{k}\left\langle u_{k}, u_{i}\right\rangle \alpha_{i}\right) . \tag{14}
\end{equation*}
$$

Proof. If $\alpha=\left(\left\langle x, u_{1}\right\rangle, \ldots,\left\langle x, u_{k}\right\rangle\right) \in \mathbb{E}_{k}^{\|}$then

$$
\kappa \sum_{i=1}^{k}\left\langle u_{j}, u_{i}\right\rangle \alpha_{i}=\kappa \sum_{i=1}^{k}\left\langle u_{j}, u_{i}\right\rangle\left\langle x, u_{i}\right\rangle=\left\langle x, u_{j}\right\rangle
$$

for all $j \in\{1,2, \ldots, k\}$, that is, $\pi \alpha=\alpha$. For $\alpha \in \mathbb{E}_{k}^{\perp}$, from the relation

$$
\kappa \sum_{i=1}^{k}\left\langle u_{j}, u_{i}\right\rangle \alpha_{i}=\kappa\left\langle u_{j}, \sum_{i=1}^{k} \alpha_{i} u_{i}\right\rangle=0
$$

satisfied for all $j \in\{1,2, \ldots, k\}$, it follows that $\pi \alpha=0$.

Lemma 4. The isometry

$$
\begin{equation*}
S: \mathbb{E}_{n} \longrightarrow \mathbb{E}_{k}^{\|} \quad S x=\left(\sqrt{\kappa}\left\langle x, u_{1}\right\rangle, \ldots, \sqrt{\kappa}\left\langle x, u_{k}\right\rangle\right) \tag{15}
\end{equation*}
$$

is an isomorphism of representations which allows us to identify the spaces $\mathbb{E}_{n}$ and $\mathbb{E}_{k}^{\|}$.
Proof. The mapping $S$ is an isometry

$$
\langle S x, S y\rangle=\kappa \sum_{i=1}^{k}\left\langle x, u_{i}\right\rangle\left\langle y, u_{i}\right\rangle=\langle x, y\rangle
$$

and in view of (13) we have $T_{g}(S x)=S(g x)$ for any $x \in \mathbb{E}_{n}, g \in G$.
The representation of a vector $x \in \mathbb{E}_{n}$ as a linear combination of $u_{1}, u_{2}, \ldots, u_{k}$ is not unique, but the next theorem shows that the canonical representation (3) is a privileged one, namely, the sum of the square of the coefficients takes its minimal value.
Theorem 2. Let $x \in \mathbb{E}_{n}$. If $x=\sum_{i=1}^{k} \alpha_{i} u_{i}$ then

$$
\begin{align*}
& \text { (i) } \pi\left(\alpha_{1}, \ldots, \alpha_{k}\right)=\left(\kappa\left\langle x, u_{1}\right\rangle, \ldots, \kappa\left\langle x, u_{k}\right\rangle\right) \\
& \text { (ii) } \sum_{i=1}^{k} \alpha_{i}^{2} \geqslant \sum_{i=1}^{k}\left(\kappa\left\langle x, u_{i}\right\rangle\right)^{2} . \tag{16}
\end{align*}
$$

Particularly,

$$
\begin{equation*}
\pi\left(\kappa\left\langle x, u_{1}\right\rangle, \ldots, \kappa\left\langle x, u_{k}\right\rangle\right)=\left(\kappa\left\langle x, u_{1}\right\rangle, \ldots, \kappa\left\langle x, u_{k}\right\rangle\right) . \tag{17}
\end{equation*}
$$

Proof. In view of lemma 3 we obtain

$$
(\pi \alpha)_{i}=\kappa \sum_{j=1}^{k}\left\langle u_{i}, u_{j}\right\rangle \alpha_{j}=\kappa\left\langle u_{i}, \sum_{j=1}^{k} \alpha_{j} u_{j}\right\rangle=\kappa\left\langle u_{i}, x\right\rangle .
$$

Since the vectors $\pi \alpha$ and $\alpha-\pi \alpha$ are orthogonal, we obtain

$$
\sum_{i=1}^{k} \alpha_{i}^{2}=\|\alpha\|^{2}=\|\pi \alpha\|^{2}+\|\alpha-\pi \alpha\|^{2} \geqslant\|\pi \alpha\|^{2}=\sum_{i=1}^{k}\left(\kappa\left\langle x, u_{i}\right\rangle\right)^{2}
$$

The numbers $\kappa\left\langle x, u_{1}\right\rangle, \ldots, \kappa\left\langle x, u_{k}\right\rangle$ are the coordinates of $x \in \mathbb{E}_{n}$ with respect to the $\operatorname{SCV}\left\{u_{1}, \ldots, u_{k}\right\}$. One can remark that $\alpha_{1}, \ldots, \alpha_{k}$ are the coordinates of a vector $x \in \mathbb{E}_{n}$ with respect to $\left\{u_{1}, \ldots, u_{k}\right\}$ if and only if $\pi\left(\alpha_{1}, \ldots, \alpha_{k}\right)=\left(\alpha_{1}, \ldots, \alpha_{k}\right)$, that is, if and only if

$$
\begin{equation*}
\alpha_{i}=\kappa \sum_{j=1}^{k}\left\langle u_{i}, u_{j}\right\rangle \alpha_{j} \tag{18}
\end{equation*}
$$

for all $i \in\{1,2, \ldots, k\}$.
The space $\mathbb{E}_{k}$ can be identified with the space of all the functions $\varphi: M \longrightarrow \mathbb{R}$ by associating the function $\varphi_{\alpha}\left(g_{i}\right)=\alpha_{i}$ with each $\alpha \in \mathbb{E}_{k}$. In this case, denoting $\langle h \mid g\rangle=\langle\Phi(h), \Phi(g)\rangle$, relation (18) becomes

$$
\begin{equation*}
\varphi(h)=\kappa \sum_{g \in M}\langle h \mid g\rangle \varphi(g) \tag{19}
\end{equation*}
$$

in agreement with the theory of coherent states [10, relation (14)].

## 4. Description of linear operators in terms of an SCV

It is well known that an adequate description can simplify the solution of a problem. If the elements of $\mathbb{E}_{n}$ are described by using their coordinates with respect to an $\operatorname{SCV} \mathcal{C}$ then each transformation $g: \mathbb{E}_{n} \longrightarrow \mathbb{E}_{n}$ becomes a signed permutation

$$
T_{g}\left(\alpha_{1}, \alpha_{2}, \ldots, \alpha_{k}\right)=\left(s_{1}^{g} \alpha_{g^{-1}(1)}, s_{2}^{g} \alpha_{g^{-1}(2)}, \ldots, s_{k}^{g} \alpha_{g^{-1}(k)}\right)
$$

and, consequently, the form of the $G$-invariant mathematical objects (operators, equations, etc) defined on $\mathbb{E}_{n}$ becomes simpler. Some concrete applications of the description of $\mathbb{E}_{3}$ obtained by using the $\operatorname{SCV}\{(1,1,1),(1,-1,-1),(-1,1,-1),(-1,-1,1)\}$ can be found in $[2,3]$. In this section we only present some general results concerning the description of the linear operators in terms of an SCV.

Let $A: \mathbb{E}_{n} \longrightarrow \mathbb{E}_{n}$ be a linear operator, $\tilde{S}$ be the transpose of the matrix
$S=\sqrt{\kappa}\left(\begin{array}{ccc}\left\langle u_{1}, e_{1}\right\rangle & \cdots & \left\langle u_{1}, e_{n}\right\rangle \\ \cdots & \cdots & \cdots \\ \left\langle u_{k}, e_{1}\right\rangle & \cdots & \left\langle u_{k}, e_{n}\right\rangle\end{array}\right) \quad \pi=\kappa\left(\begin{array}{ccc}\left\langle u_{1}, u_{1}\right\rangle & \cdots & \left\langle u_{1}, u_{k}\right\rangle \\ \cdots & \cdots & \cdots \\ \left\langle u_{k}, u_{1}\right\rangle & \cdots & \left\langle u_{k}, u_{k}\right\rangle\end{array}\right)$
and let
$A=\left(\begin{array}{ccc}\left\langle e_{1}, A e_{1}\right\rangle & \cdots & \left\langle e_{1}, A e_{n}\right\rangle \\ \cdots & \cdots & \cdots \\ \left\langle e_{n}, A e_{1}\right\rangle & \cdots & \left\langle e_{n}, A e_{n}\right\rangle\end{array}\right) \quad A^{\prime}=\kappa\left(\begin{array}{ccc}\left\langle u_{1}, A u_{1}\right\rangle & \cdots & \left\langle u_{1}, A u_{k}\right\rangle \\ \cdots & \cdots & \cdots \\ \left\langle u_{k}, A u_{1}\right\rangle & \cdots & \left\langle u_{k}, A u_{k}\right\rangle\end{array}\right)$
be the matrices associated with our operator with respect to the canonical basis $\left\{e_{1}, \ldots, e_{n}\right\}$ and the $\operatorname{SCV} \mathcal{C}=\left\{u_{1}, \ldots, u_{k}\right\}$, respectively.

Theorem 3. We have

$$
\begin{equation*}
S \tilde{S}=\pi \quad \tilde{S} S=I \quad A^{\prime}=S A \tilde{S} \quad \operatorname{Tr} A=\operatorname{Tr} A^{\prime} \tag{20}
\end{equation*}
$$

where I is the unit matrix.

Proof. Indeed,

$$
\kappa \sum_{m=1}^{n}\left\langle u_{i}, e_{m}\right\rangle\left\langle u_{j}, e_{m}\right\rangle=\kappa\left\langle u_{i}, u_{j}\right\rangle
$$

$$
\begin{aligned}
& \kappa \sum_{m=1}^{k}\left\langle u_{m}, e_{i}\right\rangle\left\langle u_{m}, e_{j}\right\rangle=\left\langle e_{i}, e_{j}\right\rangle \\
& \kappa \sum_{j=1}^{n} \sum_{m=1}^{n}\left\langle u_{i}, e_{j}\right\rangle\left\langle e_{j}, A e_{m}\right\rangle\left\langle u_{l}, e_{m}\right\rangle=\kappa\left\langle u_{i}, A u_{l}\right\rangle
\end{aligned}
$$

and

$$
\begin{aligned}
\operatorname{Tr} A^{\prime} & =\kappa \sum_{i=1}^{k}\left\langle u_{i}, A u_{i}\right\rangle=\kappa \sum_{i=1}^{k} \sum_{j=1}^{n} \sum_{m=1}^{n}\left\langle u_{i}, e_{j}\right\rangle\left\langle e_{j}, A e_{m}\right\rangle\left\langle u_{i}, e_{m}\right\rangle \\
& =\sum_{j=1}^{n} \sum_{m=1}^{n}\left\langle e_{m}, e_{j}\right\rangle\left\langle e_{j}, A e_{m}\right\rangle=\sum_{j=1}^{n}\left\langle e_{j}, A e_{j}\right\rangle=\operatorname{Tr} A .
\end{aligned}
$$

Theorem 4. The operator $A: \mathbb{E}_{n} \longrightarrow \mathbb{E}_{n}$ is a self-adjoint operator if and only if the matrix $A^{\prime}$ is symmetric.

Proof. If $A$ is self-adjoint then $\left\langle u_{l}, A u_{m}\right\rangle=\left\langle u_{m}, A u_{l}\right\rangle$ for all $l, m \in\{1,2, \ldots, k\}$. Conversely, if this relation is satisfied, then

$$
\begin{aligned}
\left\langle e_{i}, A e_{j}\right\rangle & =\kappa^{2} \sum_{l=1}^{k} \sum_{m=1}^{k}\left\langle e_{i}, u_{l}\right\rangle\left\langle u_{l}, A u_{m}\right\rangle\left\langle e_{j}, u_{m}\right\rangle \\
& =\kappa^{2} \sum_{l=1}^{k} \sum_{m=1}^{k}\left\langle e_{i}, u_{l}\right\rangle\left\langle u_{m}, A u_{l}\right\rangle\left\langle e_{j}, u_{m}\right\rangle=\left\langle e_{j}, A e_{i}\right\rangle .
\end{aligned}
$$

Theorem 5. Any eigenvalue of $A$ is at the same time an eigenvalue of the matrix $A^{\prime}$.
Proof. If $x \in \mathbb{E}_{n}$ is an eigenvector corresponding to $\lambda$ then

$$
A^{\prime}(S x)=(S A \tilde{S})(S x)=S(A x)=S(\lambda x)=\lambda(S x)
$$

that is, $S x$ is an eigenvector of $A^{\prime}$ corresponding to the eigenvalue $\lambda$.
Theorem 6. If $A, B: \mathbb{E}_{n} \longrightarrow \mathbb{E}_{n}$ are two linear operators such that $A B=B A$, and $A^{\prime}$ and $B^{\prime}$ are the corresponding matrices with respect to $\mathcal{C}$, then $A^{\prime} B^{\prime}=B^{\prime} A^{\prime}$.

Proof. We have $A^{\prime} B^{\prime}=(S A \tilde{S})(S B \tilde{S})=S(A B) \tilde{S}=S(B A) \tilde{S}=B^{\prime} A^{\prime}$.
The derivative of a function $f: \mathbb{E}_{n} \longrightarrow \mathbb{R}$ with respect to a unit vector $v \in \mathbb{E}_{n}$ is usually defined as

$$
\frac{\partial f}{\partial v}(x)=\lim _{t \rightarrow 0} \frac{1}{t}(f(x+t v)-f(x))
$$

If $\left\|u_{1}\right\|=1$ then $\left\|u_{2}\right\|=\cdots=\left\|u_{k}\right\|=1$, and we have the relations

$$
\begin{equation*}
\frac{\partial}{\partial u_{i}}=\sum_{j=1}^{n}\left\langle u_{i}, e_{j}\right\rangle \frac{\partial}{\partial e_{j}} \quad \frac{\partial}{\partial e_{i}}=\kappa \sum_{j=1}^{k}\left\langle e_{i}, u_{j}\right\rangle \frac{\partial}{\partial u_{j}} \tag{21}
\end{equation*}
$$

which are useful in the case of differential equations and operators.
The description obtained by using an SCV can be regarded as a discrete version of the method of coherent states, and it may be a useful alternative to the usual description in certain applications. Generally, the use of an SCV leads to simpler expressions for the $G$-invariant objects, and hence a simplification of the mathematical formalism of certain models [2,3].

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